

# EFIX F8 GNSS

# **USER GUIDE**



# Survey & Engineering | June 2023

Stronger signal, easy to fix



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# Preface

EFIX

# Copyright

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# **Safety Warnings**

The Global Navigation Satellite System (GNSS) comprises several distinct satellite constellations, each of which is under the jurisdiction of a specific government entity. These entities bear the sole responsibility for ensuring the accuracy of their respective systems and for maintaining the integrity of their satellite networks.

Do not rely solely on the device for critical navigation decisions. The GNSS signals may be affected by atmospheric conditions, satellite availability, signal blockage, etc.

Be aware of the limitations of GNSS accuracy. It provides positioning information with a certain level of accuracy, but errors (including manual error) and deviations can occur.

Avoid prolonged exposure to strong magnetic fields, as they may interfere with the operation of the device and affect its accuracy.

Do not dismantle or modify the device. Any unauthorized modification may result in malfunction or damage and void the warranty.

Follow all instructions provided in the user manual for proper handling, charging, and maintenance.

# **1** Introduction

The F8 GNSS receiver removes barriers to portability without sacrificing performance. Featuring full GNSS technology, it offers best-in-class GNSS signal tracking even in a harsh environment, enabling GNSS surveying beyond usual constraints. The F8 GNSS incorporates the latest innovations such as an inertial module (IMU) providing automatic pole-tilt compensation in a very compact design.

# **1.1 Safety Information**

# **1.1.1 Warnings and Cautions**

An absence of specific alerts does not mean that there are no safety risks involved.

A Warning or Caution information is intended to minimize the risk of personal injury and/or damage to the equipment.



WARNING - A Warning alerts you to a potential misused or wrong setting of the equipment.



CAUTION - A Caution alerts you to a possible risk of serious injury to your person and/or damage to the equipment.

# 1.2 Regulations and Safety

The receivers contain a built-in wireless modem for signal communication through Bluetooth<sup>®</sup> wireless technology or through external communication datalink. Regulations regarding the use of the wireless modem vary greatly from country to country. In some countries, the unit can be used without obtaining an end-user license. However, in some countries, the administrative permissions are required. For license information, consult your local dealer. Bluetooth<sup>®</sup> operates in license-free bands.

Before operating a F8 GNSS receiver, determine if authorization or a license to operate the unit is required in your country. It is the responsibility of the end-user to obtain an operator's permit or license for the receiver for the location or country of use.

# 1.2.1 Use and Care

This receiver is designed to withstand the rough environment that typically occurs in the field. However, the receiver is high-precision electronic equipment and should be treated with reasonable care.



CAUTION - Operating or storing the receiver outside the specified temperature range will cause irreversible damage.

# **1.3 Technical Support**

If you have a problem and cannot find the information you need in this manual or EFIX website (<u>www.efix-geo.com</u>), contact your local EFIX dealer from which you purchased the receiver(s).

If you need to contact EFIX technical support, please contact us by email (<u>support@ efix-geo.com</u>) or Skype (<u>support@efix-geo.com</u>).

# **1.4 Disclaimer**

Before using the receiver, please make sure that you have read and understood this User Guide, as well as the safety information. EFIX holds no responsibility for the wrong operation by users and for the losses incurred by the wrong understanding about this User Guide. However, EFIX reserves the rights to update and optimize the contents in this guide regularly. Please contact your local EFIX dealer for new information.

# **1.5 Your Comments**

Your feedback about this user guide will help us to improve it in future revision. Please email your comments to <u>support@ efix-geo.com</u>.



# 2 Getting Started with F8

# 2.1 About the Receiver

The new F8 GNSS receiver offers integrated IMU-RTK technology to provide a robust and accurate GNSS positioning in any circumstances. Unlike the standard MEMS based GNSS receivers, the F8 GNSS IMU-RTK combines state-of-the-art GNSS RTK engine, calibration-free professional IMU sensor and advanced GNSS tracking capabilities. Survey projects are achieved with high productivity and reliability pushing the boundaries of conventional GNSS RTK survey.

The receiver can be used as the part of an RTK GNSS system with EFIX eField software. Moreover, user can download the GNSS data that recorded in the internal memory of receiver to a computer.

To configure the receiver for performing a wide variety of functions, you can use the web interface by connecting the receiver with PC or smartphone through Wi-Fi.

# 2.2 Parts of the Receiver

The operating control is located on the front panel. The main camera is located on the rear panel. The bottom camera, serial ports and connectors are located on the bottom of the unit.

### 2.2.1 Front Panel

The following figure shows a front view of the receiver. The front panel contains one Power LED Button.





	Getting Started with F8
Name	Description
Power LED Button         (Red-Green-Orange)	<ul> <li>Works as a Power button: Press and hold this button for 3 seconds to turn on or turn off the receiver.</li> <li>Works as an indicator light: <ul> <li>Power indicator light:</li> <li>Shutdown, charging flash rules: During the charging process (including connecting to a power bank), the orange light is always on, and the green light is always on when fully charged;</li> <li>Boot up, Charging flash rules: Charging alternates between green and orange.</li> </ul> </li> <li>Battery-powered: <ul> <li>when the battery level is low (less than 10%), the red light flashes once every 5 seconds, and continues to flash for 2 seconds. When the red light is flashing, the green light is off.</li> <li>RTK working process: <ul> <li>The red light flashes at 1Hz when receiving differential data; after being fixed, the green light flashes at 1Hz;</li> <li>Firmware upgrade: <ul> <li>During the upgrade, the red and green lights flash alternately at a frequency of 1Hz. After the upgrade is successful, all lights are on for 1 second and then restarted.</li> </ul> </li> </ul></li></ul></li></ul>



# 2.2.2 Front Camera and Bottom Camera

The following two figures show the rear view and bottom view of the receiver:

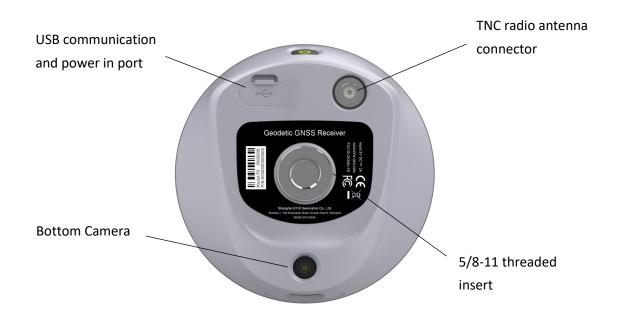


Name	Description
Front Camera	<ul> <li>Used for vision survey and vision stakeout image acquisition.</li> </ul>
Bottom Camera	<ul> <li>Used for vision stakeout image acquisition.</li> </ul>

# 2.2.3 Receiver Ports

The following figure shows a bottom view of the receiver.

The bottom panel contains USB communication and power in port, TNC radio antenna connector, 5/8-11 threaded insert and Bottom Camera.



Port	Name	Description
C Type-C	USB Type-C port	<ul> <li>This port is a USB Type-C connector that supports USB communications.</li> <li>Users can use USB Type-C Cable supplied with the system to download the logged data to a computer.</li> </ul>
	Radio antenna connector	<ul> <li>Connect a radio antenna to internal radio of the receiver. And this connector is not used if you are using an external radio.</li> </ul>

# 2.3 Batteries and Power

### 2.3.1 Built-in batteries

The receiver has two built-in 4900 mAh rechargeable Lithium-ion batteries.

# 2.3.2 Charging the Battery

The rechargeable Lithium-ion battery is supplied partially charged. Charge the battery completely before using it for the first time. Charge via USB Type-C port.



WARNING – Charge and use the rechargeable Lithium-ion battery only in strict accordance with the instructions. Charging or using the battery in unauthorized equipment can cause an explosion or fire and can result in personal injury and/or equipment damage.

To prevent injury or damage:

- Do not charge or use the battery if it appears to be damaged or leaking.
- Charge the Lithium-ion battery only in a EFIX product that is specified to charge it. Be sure to follow all instructions that are provided with the battery charger.
- Discontinue charging a battery that gives off extreme heat or a burning odor.
- Use the battery only in EFIX equipment that is specified to use it.
- Use the battery only for its intended use and according to the instructions in the product documentation.

# 2.3.3 Battery Safe

WARNING – Do not damage the rechargeable Lithium-ion battery. A damaged battery can cause an explosion or fire and can result in personal injury and/or property damage.

To prevent injury or damage:

- Do not expose the battery to fire, high temperature, or direct sunlight.
- Do not immerse the battery in water.
- Do not drop or puncture the battery.



# 2.3.4 External Power Supply

Provide the external power to the receiver by the USB Type-C Cable + Power Adapter.

The Power Adapter is connecting with AC power of 100-240V, the output port of the Power Adapter connects with the USB Type-C Cable.



# 2.4 Product Basic Supply Accessories

# 2.4.1 Rover Kit Basic Supply

Item	Picture
F8 GNSS Receiver	EFIX
UHF Bar Antenna (410-470 MHz)	
eField USB Type-C	
Tribrach adaptor	
2M Range Pole w/bag	·
Auxiliary H.I. Tool	



Getting Started with F8



# **2.5 Connecting to an Office Computer**

The receiver can be connected to an office computer via a eField USB Type-C. Before you connect to the office computer, ensure that the receiver is powered on.

The following figure shows how to connect to the computer for serial data transfer or settings:



# 2.6 Connecting to a Controller

# 2.6.1 Connecting via Wi-Fi with eField Software

Turn on the controller  $\rightarrow$  run eField $\rightarrow$  go to **Config** main menu  $\rightarrow$  tap **Connect**.

In the *Connect* screen, select **EFIX** for the *Brand* field, **F8** for *Device Type* field, **WIFI** for *Connection Type* field.



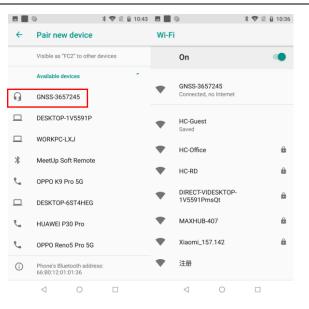
Getting Started with F8

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← test-Conn	ect instrumen	ts
GNSS	Per	ipheral
Brand	EFIX	
Туре	RTK	
Model	F8	~
Contact type	Wi-Fi	
Antenna type	EFIXF8 NONE	>
Target		
Click to select	t Wi-Fi	>
	Connect	
$\triangleleft$	0	

Tap the Click to select WI-FI to select the hot spot  $\rightarrow$  Switch on the WiFi module by the top switch  $\rightarrow$ Tap Pair new device  $\rightarrow$ select the target device in the list  $\rightarrow$  Tap back button  $\rightarrow$  select the target device in the WIFI target list  $\rightarrow$  Tap the **Connect** button to build the connection.

		* 🖹 🗎 10:3	87 🖪 📕	•	*	💎 🖹 🔒 10:43
Wi-Fi			Blue	tooth		
Off	f			On		
То	see availabl	e networks, turn		Visible as "FC2	2" to other dev	ices
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app Wi-l	is and service Fi networks. Y	ion accuracy, system is can still scan for 'ou can change this	+	Pair new dev	rice	
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**Tip** –Tap **Connect** to link to the hot spot. If the first-time connection to this hot spot, user may type in the password. The Wi-Fi key of the receiver is **12345678** by default.

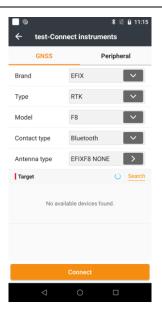
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Brand	EFIX	~	Brand	EFIX	~
Туре	RTK	×	Туре	RTK	~
Model	F8	×	Model	F8	×
Contact type	Wi-Fi	~	Contact type	Wi-Fi	~
Antenna type	EFIXF8 NONE	>	Antenna type	EFIXF8 NONE	>
Target			Target		
🕤 GNSS-3657	245	>	ᅙ GNSS-3657	245	>
	Connect			Disconnect	
$\bigtriangledown$	0		$\bigtriangledown$	0	

### 2.6.2 Connecting via Bluetooth with eField Software

Turn on the controller  $\rightarrow$  run eField  $\rightarrow$  go to **Config** main menu  $\rightarrow$  tap **Connect**.

In the *Connect* screen, select EFIX for the *Brand* field, **F8** for *Device Type* field, **Bluetooth** for *Connection Type* field.





Tap the **Search** to search Bluetooth device around  $\rightarrow$  Switch on the Bluetooth module by the top switch  $\rightarrow$  Tap Pair new device  $\rightarrow$  select the target device in the list  $\rightarrow$  Tap back button  $\rightarrow$  select the target device in the Bluetooth target list  $\rightarrow$  Tap the **Connect** button to build the connection.

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Blue	tooth		←	Pair new device	
	On	•		Visible as "FC2" to other of	devices
	Visible as "FC2" to other	devices		Available devices	÷
	Paired devices		G	GNSS-3657245	
+	Pair new device			DESKTOP-1V5591P	
	Device name			WORKPC-LXJ	
	FC2		*	MeetUp Soft Remote	
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Getting Started with F8

← test-Cor	nnect instruments		← test-Cor	nnect instrume	nts
GNSS	Periph	eral	GNSS	Pe	ripheral
Brand	EFIX		Brand	EFIX	~
Туре	RTK		Туре	RTK	
Model	F8	~	Model	F8	~
Contact type	Bluetooth	~	Contact type	Bluetooth	~
Antenna type	EFIXF8 NONE		Antenna type	EFIXF8 NONE	
Target	C	Search	Target		O Search
🛞 GNSS-3657	245	0	🛞 GNSS-3657	7245	C
	Connect			Disconnect	
$\bigtriangledown$	0 0		$\triangleleft$	0	

# 2.7 Downloading Logged Data

Data logging involves the collection of GNSS measurement data over a period at a static point or points, and subsequent post-processing of the information to accurately compute baseline information. Data logging using receivers requires access to suitable GNSS post-processing software such as the eOffice Software.

# 2.7.1 FTP Download

The procedures of downloading logged data through FTP are as follows:

(1) Switch on the receiver, search its Wi-Fi in the computer and connect.

(2) After the successful connection, open the file manager in the computer and input "ftp:\\192.168.1.1" in the address box.

👺   🛃 🚽   192.168.1.1					
File	Home	Share	View		
$\leftarrow \  \  \rightarrow$	· 🛧 💈	🕨 👌 🕨	nternet >	192.168.1.1	~

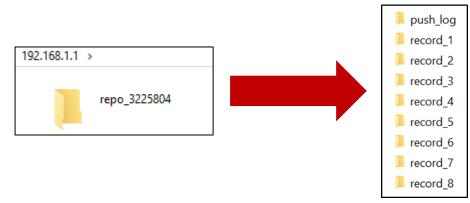
(3) Input user name and password, the default user name and password are "ftp".



Getting Started with F8

Log On a	As				×	
?	Either the server does not allow anonymous logins or the e-mail address was not accepted					te
	FTP server:	192.168.1.1				
	<u>U</u> ser name:	ftp			~	
	Password:	•••				
	After you log or	you log on, you can add this server to your Favorites and return to it easily.				
⚠	FTP does not encrypt or encode passwords or data before sending them to the server. To protect the security of your passwords and data, use WebDAV instead.					
	Log on <u>a</u> nonymously Save password					
				Log On	Cancel	

(4) Double click the folder "repo\_receiver SN" (take 3225804 as example), you will see 9 folders. The "push\_log" folder is used to save the log files, and the other 8 folders represent different logging sessions and are used for store static data.



(5) Double click the folder that you have configured to store the static data, you will see the folder(s) created by the F8 system automatically and named by the date which is decide by GPS time when you start to log data.



(6) Select the destination folder and double click it, two folders named as different data format (ecn and rinex) will be displayed.





(7) Select the data format that you configured to save the static data, you will find the static raw data.

3689191165K.ECN

**Notes**: For ecn files, the name of the file is represented as XXXXXDDDNN, where XXXXXX is the SN of the receiver, DDD is day of year, and NN is the recording session.

WARNING – The static data will be saved in the first logging session, the "record\_1" folder, by default. Old files will be deleted if the storage space is full. If you configure not to auto delete old files when the memory is low, the receiver will stop data logging.



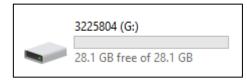
# 2.7.2 Web Server Download

The procedures of downloading logged data through web server refer to 5.4.4 Data Download Submenu.

# 2.7.3 USB Download

The procedures of downloading logged data in the receiver are as follows:

(1) Switch on the receiver and connect it with a computer by eField Type-C. After the successful connection, a removable disk named as the Serial Number (SN) of the receiver will appear on the computer.



(2) Double click the removable disk and you will see the folder named as "repo".

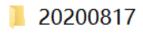


(3) Double click this folder, you will see 9 folders. The "push\_log" folder is used to save the log files, and the other 8 folders represent different logging session and are used for store static data.

 Image: static data.



(4) Double click the folder that you have configured to store the static data, you will see the folder(s) created by the F8 system automatically and named by the date which is decide by GPS time when you start to log data.





(5) Select the destination folder and double click it, and then two folders named as different data format (ecn and rinex) will be displayed.



(6) Select the data format that you have configured to save the static data, you will find the static raw data.



Tip – For ecn files, the name of the file is represented as XXXXXDDDNN, where XXXXXX is the SN of the receiver, DDD is day of year, and NN is the recording session.

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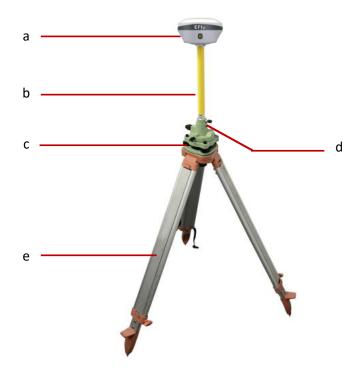


# **3** Equipment Setup and Operation

# 3.1 Post-processing Base Station Setup

For good performance, the following base station setup guidelines are recommended:

### Components:



No.	Name
а	F8 GNSS receiver
b	Extension pole (30 cm)
с	Tribrach adaptor
d	Tribrach w/ Opti
е	Aluminum tripod

#### Steps:

- (1) Put tripod in the target position, center and level it roughly.
- (2) Place and lock the tribrach in the tripod.



- (3) Screw the receiver onto the tribrach.
- (4) Center and level the receiver more precisely.
- (5) Connect the receiver to external battery by using USB Type-C cable if necessary.
- (6) Turn on the receiver by pressing the power button for 3 s.
- (7) Measure the antenna height by using H.I. tape and auxiliary H.I. tool.
- (8) Press the function button to select Data to start recording static raw.

#### If work with a data controller:

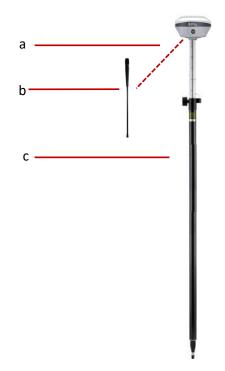
- (9) Switch on the data controller and connect it to the receiver.
- (10) Use software to configure the receiver as static mode.



# 3.2 Real-Time Rover Station Setup

For good performance, the following rover station setup guidelines are recommended:

#### Components



No.	Name
а	F8 GNSS receiver
b	UHF whip antenna
С	2M range pole w/bag

Steps:

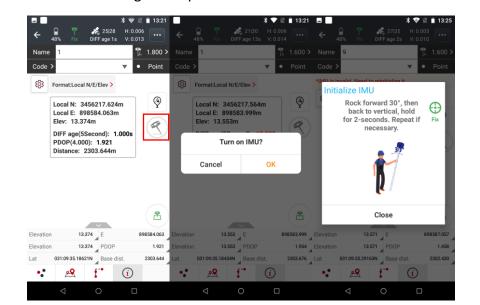
- (1) Connect the UHF whip antenna to the receiver.
- (2) Screw the receiver onto the pole.
- (3) Turn on the receiver by pressing the power button for 3 s.
- (4) Switch on the data controller and connect it to the receiver.
- (5) Use software to configure the receiver as rover mode.
- (6) Center and level the receiver more precisely.
- (7) Use software to start survey.

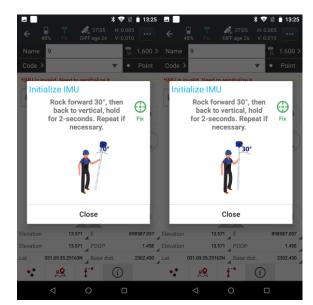


# **3.3 Working with the Tilt Compensation**

### 3.3.1 Operation Steps

(1) Open eField-> Tap PT Survey-> Tap to activate tilt measurement.
(2) Shake around according to the procedures in the interface to do initialization.





(3) This icon < will appear when the initialization is successful.





(4) Enter the Name and Antenna, then tap Points automatically.

point will be collected and store to

(5) When this icon *eq* appears, the text will show "\*IMU is invalid. Need to reinitialize it." at the top of interface.

ß



to close tilt compensation. (6) Tap 📿

# 3.3.2 Notes of using tilt measurement

1. At the beginning of initialization, the pole height of the instrument should be the same as that antenna height in the software.

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2. In the process of tilt measurement, if the controller shows that "Tilt is not available, please measure in alignment" (red), please shake RTK slightly from left to right or back to front until the reminder disappears.

3. The controller will prompt "Tilt is not available, please measure in alignment" when the receiver is stationary over 30 seconds or the pole hit the ground toughly.

4. The pole cannot be shaken when point is collected.

5. The receiver cannot be moved in a circle in one direction for more than 360 degrees. if the receiver has been rotated 360 degrees, it must be rotated in the opposite direction to recover again.

6. Initialization is required:

- when the RTK is turned on every time;
- when IMU module is turned on every time;
- when receiver drops at working;
- when the pole is tilted more than 65 degree;
- when the receiver is stationary more than 10 minutes;
- when the RTK rotates too fast on the matching pole (2 rounds per second);
- when the pole hit the ground toughly.

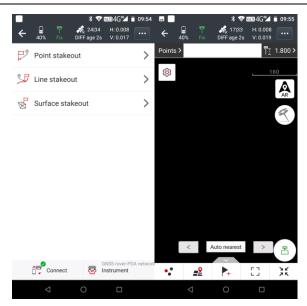
# 3.4 Working with the Vision Camera

### 3.4.1 Operation Steps

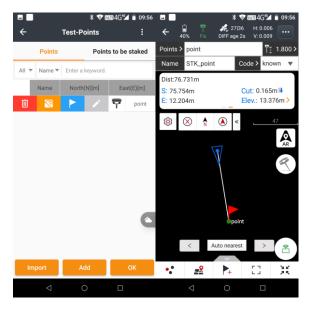
### 3.4.1.1 Vision Stakeout

 (1) Open eField-> Tap Stakeout-> Tap Point stakeout (Here take point stakeout as an example, currently also supports Line stakeout, Cad stakeout)



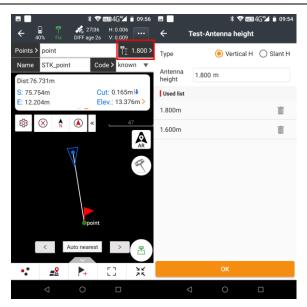


(2) Tap points, select a stakeout point, slide right and tap stakeout



(3) Check whether the height of the antenna is consistent with the height of the 2M Range Pole w/ Bag





(4) Tap AR, the software will prompt you to activate tilt measurement

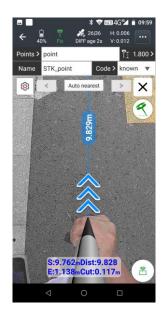


- (5) This icon *exactly* will appear when the initialization is successful.
- (6) If the distance to the target is less than 50.0m meters, it will automatically switch to Vision Stakeout. (with Front Camera)



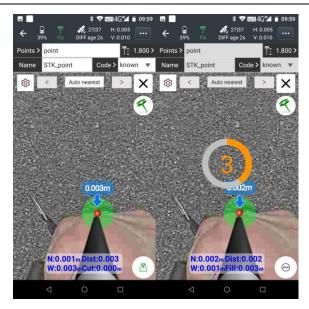


- (7) If the distance to the target is less than 10.0m meters, it will automatically switch to Vision Stakeout. (with Front Camera)
- (8) If the distance to the target is less than 10.0m meters, it will automatically switch to Vision Stakeout. (with Bottom Camera)



(9) After we are within 1cm from the target point, we can click the measurement icon to collect



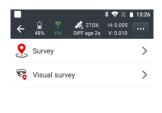


#### Note:

When the stakeout target point has a height, it is necessary to input the height of the target point as 0 or the actual height

### 3.4.1.2 Vision Survey

(1) Open eField-> Tap Survey-> Tap Vision Survey





(2) Click the red dot, the software will prompt you to activate tilt measurement.

### Note:



modify the height of the antenna to be the same as the height of the 2M Range Pole w/ Bag before initialization.

At present, the non-inductive inertial navigation is used, and the initialization can be completed by simply shaking it or walking around; after the initialization is completed, try to walk about 5m so Initialization remains stable.)



(3) After the initialization is successful, you can see the image captured by the front camera of the receiver on the screen of the controller.



(4) Enter task name.



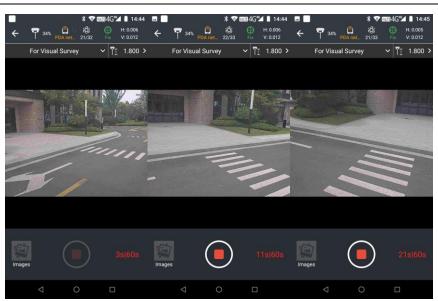


(5) Aim the camera of the receiver at the target to be tested, click the video recording icon, and there will be three seconds of preparation time.



(6) In three seconds, the video recording will begin. While circling around the target point, capture footage of the object being tested.







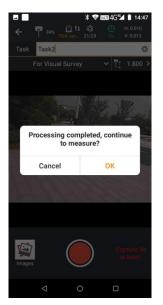
### (Note:

Maintain a constant speed while filming, and the video must not be less than 5 seconds long. The horizontal (walking direction) distance must be greater than 4 meters, and the vertical (target direction) distance must be greater than 2 meters. It is best to ensure that the vertical distance is within 15 meters.)



▽	▽	
$\nabla$	⊽	Recommended shooting route
E. E. Community	the for the second seco	
<b>v</b> v		
	0	wrong shooting route

(7) After finishing the shooting, click on the icon to end the recording and confirm the data processing. The software will automatically process the data.



(Note:

local calculation is slower, with approximately 1 minute of calculation time for every 10 seconds of data, and about 5 minutes for every 60 seconds of data.)



(8) After the calculation is completed, select the photo where the target point is located, zoom in/out the photo, and capture the corresponding point (preferably the image facing the target being tested).

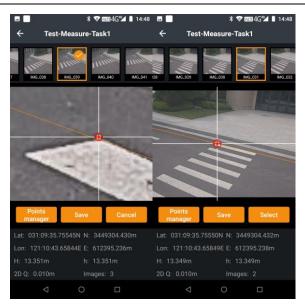


(9) After moving the target point to the arrow and clicking 'Select', the latitude, longitude, and plane coordinates of the point will be displayed below. The 2D quality represents the accuracy of the target point calculation.



Capturing the same location on multiple photos will improve the accuracy of the target point, and the 2D value will gradually decrease.





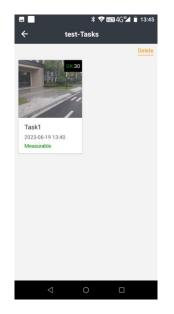
(10)When the accuracy meets the requirements, click 'Save' and enter a name for the point to save the target point in the point management system. After saving, you can click on the point library to enter the point management to view the coordinates that were just saved. If other points are needed, continue to select and save the data.





		* 🐨 📖 4	4G"⊿ 📋 14:50		,	\$ 🐨 🎟 46*24	14:50			* 💎 🎫 4	
÷		Test-Points		÷	Test-Poir	nts		÷	Test-F	oints	
	Points	Points to	o be staked	Po	ints	Points to be s	staked		Points	Points to	be staked
All 🔻	Name 🔻	Enter a keyword.		All 🔻 Nar	me 🔻 🛛 Enter a key	word.		All 🔻	Name 🔻 🛛 Enter a	keyword.	
	Name	North(N)[m]	East(E)[m]	orth(N)[m]	East(E)[m]	Elevation[m]	Code	Name	North(N)[m]	East(E	E)[m] Eleva
7	poinu	3449304.425	612395.240	49304.425	612395.240	13.336	known	poinu	3449304.42	5 61239	5.240 13
7	vrtk_1	3449304.430	612395.236	49304.430	612395.236	13.351		vrtk_1	3449304.43	61239	5.236 13
			0				0				
Im	port	Export	Add	Import	Expor	t A	dd	Imp	ort Ex	port	Add

(11)Post-calculation can also be performed, and the image library can be opened in the office for post-calculation.



## 3.4.1.3 3D Modeling

(1) Open eField-> Tap Survey-> Tap Vision Survey



Equipment Setup and Operation





(2) Click for vision survey and change to for 3D modeling



(3) Click the red dot, the software will prompt you to activate tilt measurement

#### (Note:

modify the height of the antenna to be the same as the height of the 2M Range Pole w/ Bag before initialization.

At present, the non-inductive inertial navigation is used, and the initialization can be completed by simply shaking it or walking around; after the initialization is completed, try to walk about 5m so Initialization remains stable.)

(4) After the initialization is successful, you can see the image captured by the front camera of the receiver on the screen of the controller



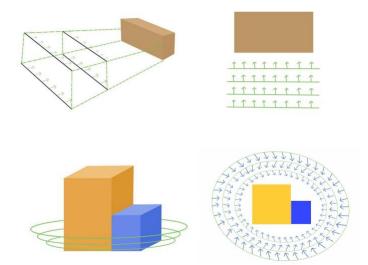
- (5) Enter task name
- (6) Aim the camera of the receiver at the target to be tested, click the video recording icon, and there will be three seconds of preparation time
- (7) The video recording will start in three seconds, while moving around the target point to shoot the object being measured. The shooting duration should not be less than five seconds. (Note: The maximum observation time is 60 minutes)
- (8) After the shooting is over, click the icon to end the recording to complete the recording

#### Note:

Please maintain a steady speed while filming, with a minimum video length of 5 seconds. The route of travel may follow the example, and it is recommended to film from various heights, angles, and distances to capture the test target.

If the target is single-sided, it is recommended to take a direct shot. If the target is a building panorama, it is recommended to take a panoramic shot, with the camera angled at a certain degree (30°-45°) from the target.

See the diagram below for reference:

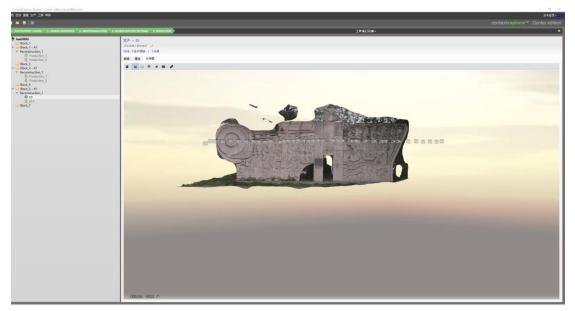


(9) Data export: Open the "File" section in the controller to find the captured image data in the following file path: "Efield\EF\_Projects\ProjectFolder\ImageTask\Task Folder".

The "images" folder under the current folder contains the captured photos, while the "camera.txt" file is the camera parameter file. When exporting data, both of these data files need to be copied and pasted onto the computer.



(10)Use third-party modeling software for model building.







## 3.4.2 Notes of using Vision Camera

1. At the beginning of initialization, the pole height of the instrument should be the same as that antenna height in the software.

2. In the process of tilt measurement, if the controller shows that "Tilt is not available, please measure in alignment" (red), please shake RTK slightly from left to right or back to front until the reminder disappears.

3. The controller will prompt "Tilt is not available, please measure in alignment" when the receiver is stationary over 30 seconds or the pole hit the ground toughly.

4. The pole cannot be shaken when point is collected.

5. The receiver cannot be moved in a circle in one direction for more than 360 degrees. if the receiver has been rotated 360 degrees, it must be rotated in the opposite

direction to recover again.

6. Initialization is required:

- when the RTK is turned on every time;
- when IMU module is turned on every time;
- when receiver drops at working;
- when the pole is tilted more than 65 degree;
- when the receiver is stationary more than 10 minutes;
- when the RTK rotates too fast on the matching pole (2 rounds per second);
- when the pole hit the ground toughly.

7.Ensure stable fixed solutions by walking and filming in open areas using Vision RTK.

8. Try to capture Visually rich textures and lines by adjusting filming angles and distances to enhance the field of view.

9. Avoid filming dynamic objects that create reflective glare, such as glass surfaces, water reflections, moving objects, cars, or pedestrians.

10.Film under good lighting conditions as much as possible and avoid filming in low light, strong light, or backlights.

11.Increase the line of sight between the target points and the filming route as much as possible while avoiding obstructions in the middle.

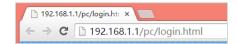


Supported browsers:

- Google Chrome
- Microsoft Internet Explorer<sup>®</sup> version 10, or higher

To connect to the receiver through a web browser:

- 1. Turn on the Wi-Fi of the receiver.
- 2. Search the wireless network named as GNSS-XXXXXXX (the SN of your receiver) on your computer, and then establish the connection.
- 3. After the successful connection between your computer and the receiver, enter the IP address (192.168.1.1) of the receiver into the address bar of the web browser on your computer:



4. The web browser prompts you to enter a login account and password:

ODI000010101000010101000         0101         0	
	Login Account
	Password
	remember me
	Please Use Chrome, IE10+ or Safari

The default login account for the receiver is:

- Login Account: admin
- Password: password

**Note** – Tick **remember me** option, and then the browser will remember the Login Account and Password you entered.



5. Once you log in, the web page appears as follows:

EFIX				SN:3269707	EFI2 English V	Quit
🗑 Status	Position ×					
Position	-					
<ul> <li>Activity</li> </ul>	Position		DOP			
		31°9'57.37567445"(North)		PDOP: 1.287859		
<ul> <li>Google Map</li> </ul>	Longitude:	121°17'16.82551407"(East)		HDOP: 0.650867		
	Height:	34.505		VDOP: 1.111285		
	Туре:	Single		TDOP: 0.738674		
	Satellite Used: 30Total		Partallitan	Tracked: 48Total		
	Satellite Useu. So lotal		Satellites	Irackeu. 48 Iotai		
	GPS(9):	3,4,16,22,26,27,29,31,32	GPS(9);	3,4,16,22,26,27,29,31,32		
		3,4,5,14,15,17,23,24		3,4,5,14,15,17,23,24		
		6,7,9,16,25,39,40		1,2,3,4,5,6,7,9,10,11,12,14,16,23,24,25,32,33	34.39.40.41.44.59.60	
		1,4,14,19,21,31		1,4,14,19,21,31		
Satellites	SBAS(0):		SBAS(0):			
🔆 Receiver Configuration						1
Data Recording	Receiver Clock		ſ			
I/O Settings	GPS Week:					
Network Setting	GPS Seconds:	191444	J			
8 Module Setting						

This web page shows the configuration menus on the left of the browser window, and the setting on the right. Each configuration menu contains the related Submenus to configure the receiver and monitor receiver performance.

This chapter describes each configuration menu.

To view the web page in another language, select the corresponding language name from the dropdown list on the upper right corner of the web page.

Currently, six languages are available:



### 4.1 Status Menu

This menu provides a quick link to review the receiver's position information, satellites tracked, runtime, current data log status, current outputs, available memory, and more.



### 4.1.1 Position Submenu

This page shows the relevant position information about the receiver's position solution which including the position, DOP values, satellites used and tracked, and the receiver clock information.



## 4.1.2 Activity Submenu

Lists several important items to help you understand how the receiver is being used and its current operating condition. Items include the identities of currently tracked satellites, internal and external storage usage rate, how long the receiver has been operational, state of the internal battery, power source state. With this information, it is easy to tell exactly what functions the receiver is performing:

GPS(8): 2,5,6,7,13,15,29,30 GLONASS(5): 1,2,17,23,24 BDS(21): 1,2,3,4,5,6,8,9,10,13,16,19,20,22,29,30,35,38,39,59,60 GALLLEO(5): 7,13,19,26,33 SBAS(0):	Current Time: 2020-08-12 06:43:06 (UTC) Operation Duration: 00-00-00 00:32:45 Internal Storage: 2.59% 175MBi6750MB External Storage: 0% Disconnected External Power: Connected Battery: 82%
---	--



## 4.1.3 Google Map Submenu



Tap this submenu to show the location of the receiver on Google map.

## 4.2 Satellites Menu

Use the Satellites menu to view satellite tracking details and enable/disable GPS, GLONASS, BDS and Galileo constellations. These menus include tabular and graphical displays to provide all required information on satellite tracking status.



## 4.2.1 Tracking Table Submenu

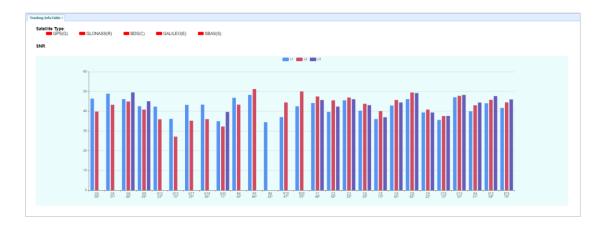
Provides the status of satellites tracked in general, such as the satellite ID, satellite type, attitude angle, azimuth angle, L1 SNR, L2 SNR, L5 SNR and enable/disable status of each one.



sv	Туре	Elevation Angle	Azimuth Angle	L1 SNR	L2 SNR	L5 SNR	Enabled
2	GPS	53	332	45.660	36.420	0.000	Yes
5	GPS	47	258	48.280	34.340	0.000	Yes
6	GPS	51	59	46.480	39.220	47.300	Yes
9	GPS	32	55	42.130	33.920	44.300	Yes
12	GPS	25	265	44.080	34.830	0.000	Yes
17	GPS	30	148	44.390	33.470	0.000	Yes
19	GPS	45	147	44.230	34.510	0.000	Yes
25	GPS	10	303	37.660	31.190	39.240	Yes
4	GLONASS	42	28	46.520	47.890	0.000	Yes
5	GLONASS	81	230	47.930	51.230	0.000	Yes
19	GLONASS	51	99	35.050	46.220	0.000	Yes
20	GLONASS	50	349	40.390	50.220	0.000	Yes
1	BDS	48	146	42.080	42.740	43.530	Yes
2	BDS	36	236	37.350	40.800	40.080	No
3	BDS	52	200	43.130	42.120	44.200	Yes
4	BDS	35	122	37.550	38.470	40.850	Yes
5	BDS	15	256	33.570	35.130	34.650	No
6	BDS	40	179	38.970	38.900	41.820	Yes
7	BDS	11	195	31.840	31.010	35.650	No
8	BDS	61	15	44.190	44.860	46.650	Yes
9	BDS	20	191	36.140	35.200	36.780	Yes
10	BDS	17	217	33.330	34.840	35.540	No
13	BDS	52	331	44.300	42.940	45.260	Yes
4	GALILEO	26	203	37.790	40.350	34.420	Yes
12	GALILEO	54	335	41.650	43.420	39.840	No
19	GALILEO	73	132	39.940	42.290	39.230	Yes

## 4.2.2 Tracking Info. Table Submenu

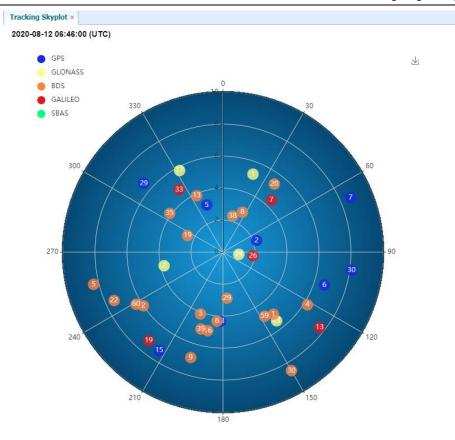
The following figure is an example of satellite track diagram page. Users can determine the satellite types and the corresponding SNR of L-band carriers to be displayed in any combination.



## 4.2.3 Tracking Skyplot Submenu

The following figure is an example of Skyplot page.





## 4.2.4 Satellite Activation Submenu

Use this menu to enable or disable satellites.

Select All		SBAS 🔲 Enable All 🔲 Disable	e All
Satellite Id	Enable	Satellite Id	Enable
1		2	
3		4	
5	•	6	
7		8	
9		10	
11		12	
13		14	
15		16	•
17		18	
19		20	
21		22	
23		24	•
25		26	
27		28	•
29		30	
31		32	



## 4.3 Receiver Configuration Menu

Use this menu to configure settings such as the antenna type and height, elevation mask and PDOP setting, the reference station coordinates, receiver resetting and web interface language:

	Receiver Configuration					
×	Description					
۲	Antenna Configuration					
۲	Reference Station Settings					
۲	Receiver Reset					
۲	Language					
۲	User Management					
۲	USB Function Switch					
۲	HCPPP Settings					
٠	1PPS Settings					

## 4.3.1 Description

This submenu shows the receiver information and reference station information, including antenna related information, elevation mask angle, reference station work mode and position, etc.

nfo		Reference Station Info	
Antenna Type:	F7	Reference Station Mode:	Auto Rover
Antenna SN:	3269707	Reference Latitude:	0°0'0.00000000"(South)
Measure Way:	Antenna Phase Center	Reference Longitude:	0°0'0.00000000"(West)
Antenna Height:	2.0000(Meter)	Reference Height:	0.0000
Elevation Mask:	10		
PDOP Mask:	99		

### 4.3.2 Antenna Configuration Submenu

Use this screen to configure all the items related to the GNSS antenna. You must enter the correct values for all antenna-related fields, because the choices you make affect the accuracy for logged data and broadcast correction data significantly:



Antenna Configuration × Antenna Configuration			
Measure Way:	Antenna Phase Center	~	
Antenna manufacturer:	EFIX	~	
Antenna Type:	F7	~	
Antenna SN:	3269707		
Antenna Height:	2.0000		(Meter)
Elevation Mask:	10		
PDOP Mask:	99		]
	Save		

#### 4.3.3 Reference Station Settings Submenu

Use this screen to configure settings such as the station coordinates and the broadcast station identifiers. You must enter accurate information in these fields, as this data affects the accuracy of logged data files and broadcast correction data significantly:

#### For Reference Station Mode:

There are three modes available:

a) **Auto Rover:** The receiver will serve as a rover after this mode is enabled, and then receive correction data through the working mode set last time.

Reference Station Settings ×	
Reference Station Mode:	Auto Rover 🗸
	Save
Sample for Average	
Positioning Constraint:	Single Solution Coordinates     Fixed Solution Coordinates
Sampling Amount:	300 0%
	• Start (1) Stop



## 4.3.4 Receiver Reset Submenu

Use this screen to completely or partially reset the receiver:

⊘ Confirm
⊘ Confirm
⊘ Confirm
⊘ Confirm

## 4.3.5 Languages Submenu

Use this screen to select the web interface language:

anguage ×		
	English	🕑 Confirm
	中文	
	Nederland	
	English	
	Русский	
	Türkçe	
	Español	
		-

## 4.3.6 User Management Submenu

r Management ×					
User Management					
▲ Add a Save The Delete Modify Anti-theft password					
ID	User Name	Password			
1	admin	••••••			
2	admin1	•••••			
3	admin2	•••••			

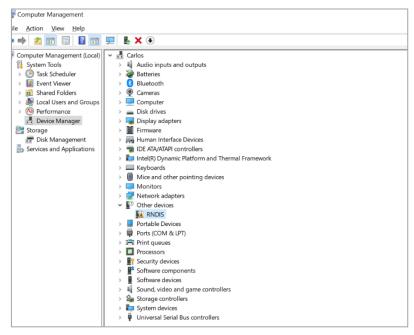


## 4.3.7 USB Function Switch

Use this screen to set F8 work as APIS base.

ø	Status	USB Function Switch ×
\$	Satellites	USB Function Switch: 💿 USB personal area network OMultimedia storage
×	Receiver Configuration	
	Description	
•	Antenna Configuration	
	Reference Station Settings	
	Receiver Reset	
,	Language	
,	User Management	
	• USB Function Switch	
	<ul> <li>HCPPP Settings</li> </ul>	

1. Connect F8 to PC by USB cable, it will shown in device manager as unknown device: RNDIS

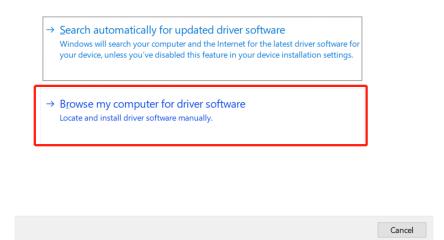


- 2. Install the driver for F8 RNDIS
  - a) Right click RNDIS, and select update driver, and choose Browse my computer for driver software.



- 1	Update Drivers - RNDIS

How do you want to search for drivers?



b) Select Let me pick from a list of available drivers on my computer, and click next

	or drivers on yo			
	rivers in this locatio	en: pols\QFIL tools\Qualcom	m ush driver v	Browse
Include s	ubfolders			
→ <u>L</u> et n		ist of available driv		CALCULATION OF THE OWNER OWNER OF THE OWNER OWNER OF THE OWNER OWNE

c) Then there will appear a hardware type list. In the list, select Network adapters.



← 📱 Update Drivers - RNDIS

Select your device's type from the list below.

Monitors	^
Multifunction adapters	
🛱 Multi-port serial adapters	
Network adapters	
Pretwork Client	
💶 Network Protocol	
P Network Service	
📦 Non-Plug and Play drivers	
OPOS Legacy Device	
PCMCIA adapters	
🕌 Persistent memory disks	
Portable Devices	
🐺 Ports (COM & LPT)	~

d) Then find Microsoft in the Manufacturer list, and select Remote NDIS based Internet Sharing Device in the model list.

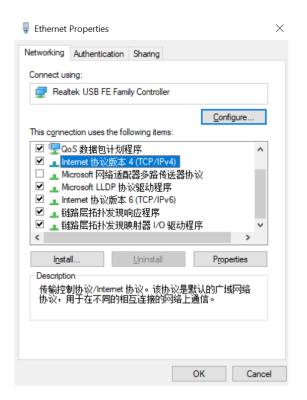
Select the device driver y	ou wa	ant to install for this hardware.		
		model of your hardware device and then click you want to install, click Have Disk.	Next. If you have a	1
Manufacturer Microsoft Microsoft Microsoft Corporation Motorola, Inc.	*	Model OpenCable Receiver Preproduction Test I RAS Async Adapter Remote NDIS based Internet Sharing Dev Remote NDIS Compatible Device Surface Ethernet Adapter	_	^
This driver is digitally signed Tell me why driver signing	ed.		<u>H</u> ave Disk	

- 3. Config IP for F8.
  - a) After installing the driver, there will show another Ethernet connection in Network connections.



Eth	ernet
朢	Unidentified network No Internet
即	Network Connected

b) Go to properties, and double click IPV4 to change the IP address.



c) Change the IP address, Subnet mask and Default gateway as following:



Internet 协议版本 4 (TCP/IPv4) Proper	rties ×	
General		
You can get IP settings assigned auton this capability. Otherwise, you need to for the appropriate IP settings.		
Obtain an IP address automatical	ly	
• Use the following IP address:		
IP address:	192 . 168 . 253 . 3	
Subnet mask:	255.255.255.0	
Default gateway:	192 . 168 . 253 . 1	
Obtain DNS server address autom	natically	
• Use the following DNS server add	resses:	
Preferred DNS server:		
Alternate DNS server:		
Ualidate settings upon exit	Ad <u>v</u> anced	
	OK Cancel	

4.Login into F8 webpage in Chrome by inputting: 192.168.253.1, keep same as the default gateway.



5.Config F8 to connect Wifi and work as APIS base.

a) Go to Module Setting -> WiFi, change WiFi mode to WiFi Terminal.

EFIX	
🥶 Status	WITH N
Satelites	WFI
🗶 Receiver Configuration	
📧 Data Recording	Power Status: DN
I/O Settings	Auto Start 🔹 Yes 🔿 No
<ul> <li>Network Setting</li> </ul>	
SS Module Sutting	With Mode: Access Point
<ul> <li>Description</li> </ul>	SSID: GNSS-3288707
• wri	
<ul> <li>Bluetaoth Settings</li> </ul>	🖽 Start
<ul> <li>Rado Settings</li> </ul>	

b) Click Start to searching the wifi and connect.



WiFi	
Power S	tatus: ON
Auto	Start:   Yes  No
Wifi	Mode: WiFi Terminal V 🕒 Searching
GNSS-0	012306
GNSS-3	266887
ZZD-4G	-UFI-E4A8
GNSS-3	266886
151851	4
Pass	word Connect
Lionel	
GNSS-3	000213
GNSS-3	219107
GNSS-3	264994
GNSS-3	268002

 c) Go to Receiver Configuration -> Reference Station Settings. Set F8 as auto base, and get the base station.

🗊 Status	Reference Station Settings ×	
እ Satellites		
X Receiver Configuration	Reference Station Mode:	Auto Base
<ul> <li>Description</li> </ul>	Base Station Name:	3269707
<ul> <li>Antenna Configuration</li> </ul>	Base Station ID:	3269707
Reference Station Settings	Reference Latitude:	31 ° 9 ' 57.45614189 " O N S
<ul> <li>Receiver Reset</li> </ul>	Reference Longitude:	121 ° 17 ′ 17.00726040 ″ © E 🛛 W
<ul> <li>Language</li> </ul>	Reference Height:	40.9406
<ul> <li>User Management</li> </ul>		Save
<ul> <li>USB Function Switch</li> </ul>		
HCPPP Settings	Sample for Average Positioning Constraint:	Single Solution Coordinates     Fixed Solution Coordinates
	Sampling Amount:	300 0%
		• Start (1) Stop
📰 Data Recording		

d) Go to I/O settings, in RTK Client, config it.

👩 Status	I/O Set	tings ×				
Satellites		Туре	Description	Output	Connection Sta	Modify
X Receiver Configuration	ſ	RTK Client	211.144.120.97:95		Unconnected	Connect Disconnecting
Data Recording	2	TCP/UDP_Client1/NTRIP S	211.144.120.97:95	Differential Data:RTCM3.2	Logged In	Connect Disconnecting
I/O Settings	3	TCP/UDP_Client2/NTRIP S	192.168.3.18:9901		Unconnected	Connect Disconnecting
I/O Settings	4	TCP/UDP_Client3/NTRIP S	192.168.3.18:9902		Unconnected	Connect Disconnecting
	5	TCP/UDP_Client4/NTRIP S	192.168.3.18:990		Unconnected	Connect Disconnecting
	6	TCP/UDP_Client5/NTRIP S	192.168.3.18:9904	_	Unconnected	Connect Disconnecting
	7	TCP/UDP_Client6/NTRIP S	192.168.3.18:9905		Unconnected	Connect Disconnecting

e) Connect Connect and config it as APIS base, use local APIS address. Then click Confirm to set.

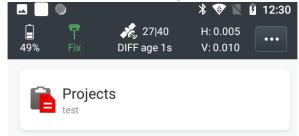


<b>QRTK</b> Client	×
Connection Protocol:	APIS_BASE V
Server IP:	211.144.120.97
Port:	9901
Differential Data:	RTCM3.2
⊗ Co	nfirm 🛞 Back

 After send correction data to APIS server successfully, the RTK Client option will become green background.

🗊 Status	I/O Set	tings ×				
🔉 Satellites		Туре	Description	Output	Connection Sta	Modify
Receiver Configuration	1	RTK Client	211.144.120.97:98	-	Logged In	Connect Disconnecting D
Data Recording	2	TCP/UDP_Client1/NTRIP S	211.144.120.97:98	Differential Data:RTCM3.2	Unconnected	Connect Disconnecting
I/O Settings	3	TCP/UDP_Client2/NTRIP S	192.168.3.18:990*		Unconnected	Connect Disconnecting D
I/O Settings	4	TCP/UDP_Client3/NTRIP S	192.168.3.18:9902		Unconnected	Connect Disconnecting D
	5	TCP/UDP_Client4/NTRIP S	192.168.3.18:990		Unconnected	Connect Disconnecting
	6	TCP/UDP_Client5/NTRIP S	192.168.3.18:9904		Unconnected	Connect Disconnecting

g) Then set rover as APIS rover, and it will get fix solution.



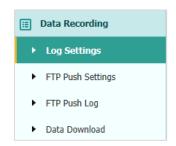
#### 4.3.8 HCPPP Settings

Reserved for HCPPP.

## 4.4 Data Recording Menu

Use the Data Logging menu to set up the receiver to log static GNSS data and to view the logging settings. You can configure settings such as observable rate, recording rate, continuous logging limit, and whether to auto delete old files when memory is low. This menu also provides the controls for the FTP push feature:





### 4.4.1 Log Settings Submenu

Here shows the data logging status, including internal and external storage usage and data logging status of each session. Also, users can configure the data logging settings for each session, including recording name, store location, storage limit, store formats, start time, etc.

itore Info								
	Position		Total Storag	e	Storage	Available		
1	Internal Storage		6750MB			6576MB		
2	External Storage		0MB		01	1B		
Record Info				recording when the st	·	Clear		
Attention: Tota Record Info Recording Numb		e should be less that Activated	n 6GB. It will stop Log Status	recording when the sto Setting Parameter	orage is full. Switch	Clear Data		

To edit the settings of each session, click the **Modify** button to the right of the required session, and then the *Recording Edit* screen appears:



Recording Edit					E
				[	
Auto Record:	⊖Yes ⊙No	Anter	nna Height:	0.0000	
Sample Interval:	1Hz	✓ Mea	asure Way:	Vertical Height	~
Elevation Mask:	15	(°) Stora	ge Format:	ECN	~
Duration Time:	60	RINE	X Version:	3.0x	~
	(Minute) 3689191base	Comp	ress Rinex Data:	⊖Yes ⊙No	
			A	dvanced	
	I	Save Save			

Click advanced to see more settings.

Start Date: 🔵 Yes 💿 No	Store Location: Internal Storage
Apply Time: 🔵 Yes 💿 No	Assigned Storage: 6000 (MB)
Integral Point Store: 🔿 Yes 💿 No	Observer: EFIX
Circulating Memory:  Yes ONO	Observe Agency: EFIX
the data overwritten first file after storage space is full Repeat Observations: Yes ONO Turn on to record a single observation. Turn off to record repeated observations.	FTP Push: Close 1:ftp server 1 2:ftp server 2 3:ftp server 3
Save	8 Back

In this screen, you can configure all the data logging parameters, and determine whether the recording files will be affected by the FTP Push. The parameters are mainly as follows:

- > Auto Record: on or off.
- Sample Interval: Select the observable rate from the dropdown list.
- **Elevation Mask**: Enter the elevation mask.
- > **Duration Time**: Set the duration of data logging.
- Site Name: Enter the name of the site.
- > Antenna Height: the measured height value.
- Measure way: Antenna Phase Center, Vertical Height, Slant Height
- Storage Format: Select the format of the data store.
- **RINEX Version**: OFF, 3.02, 2.11
- **Start Date:** Select **Yes** or **No** option to determine whether to auto record start date.
- > Apply Time: Select Yes or No option to determine whether to auto record apply time.



- Integral Point Store: Select Yes or No option to determine whether to allow receiver to save data every hour.
- Circulating Memory: Select Yes or No option to determine whether to auto delete old files if the storage space is full.
- Repeat Observations: Select Yes or No option to determine whether to turn on to record a single observation.
- Store Location: Internal Storage, External Storage.
- Assigned Storage: The assigned memory size of current thread(for example, Record 1) is 10000MB
- **Observer:** Enter the name of observer.
- **Observer Agency:** Enter the name of observer agency.
- **FTP Push**: Decide whether to push the stored files to the FTP server of your choice.

Tap Save button to save the settings and back to the *Log Settings* screen. Also, users can click Back to abandon the changed settings and back to *Log Settings* screen.

Note – To modify data logging parameters, make sure the data logging session is switched off.

To switch on or off **ANY** data logging session, tap the **ON** or **OFF** button on the right of the required session.

To delete the recorded files of **ANY** data logging session, tap the **Clear** button on the right of the required session.

To delete the recorded files of ALL data logging sessions, tap the Clear ALL Accounts button.

### 4.4.2 FTP Push Settings Submenu

Use this screen to configure the receiver to push stored files to the FTP server of your choice. Only files that are configured to use FTP push are transmitted.

Record Info				
Server ID	Server IP	Remote Directory	Server Description	Modify
1	192.168.3.72	/repo/first	ftp server 1	Modify
2	192.168.3.72	/repo/second	ftp server 2	Modify

Tap **Modify** button on the right of the required FTP server and the *FTP Push Settings* screen appears:



EFTP Push Settings
Server IP: 192.168.3.72
Port: 21
Remote Directory: /repo/first
Local directory: /mnt/repo_3225804
Server Description: ftp server 1
User Name: ftpuser1
Password:
Save Save

## 4.4.3 FTP Push Log Submenu

Shows the related information about the recorded filed that be pushed. And users can tap **Clear Ftp Send Log** button in the upper right corner to clear the log of FTP Push operations.

Server ID	Push File	File Size	Push Time	Push Successful Or Not
				Clear FTP Push
Record Info				

## 4.4.4 Data Download Submenu

In this submenu, users can download the data files that recorded in the internal storage through the internal FTP site.

1. Click this submenu, and then the log on dialogue box will prompt you to enter a user name and password:



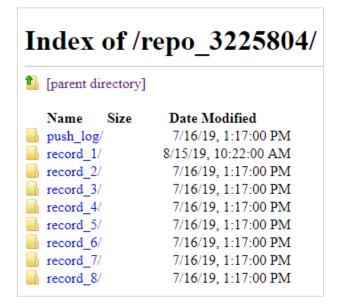
Sign in ftp://192.168				
Your connec Username	tion to this site is not	private		
Password				
			Sign in	Cancel

The default logon account for the internal FTP site is:

- User name: ftp
- Password: ftp
- 2. Click the directory named as "repo" to view and download the files currently stored on the receiver:



To find the file need to be downloaded, click the name of data logging session → the date of file that be recorded → the format of the file → the name of the target file.



 To download a file, left-click the name of the target file → download the file according to the prompts.



## 4.5 IO Settings Menu



Use the IO Settings menu to set up all receiver outputs and inputs. The receiver can output CMR, RTCM, Raw data, Ephemeris data, GPGGA, GPGSV, on TCP/IP, UDP, serial port, or Bluetooth ports.

## **4.5.1 IO Settings Submenu**

The following figure shows an example of the screen that appears when you select this submenu. (serial port setting is reserved menu)

	Туре	Description	Output	Connection Status	Modify
1	RTK Client	211.144.118.5:2102		Unconnected	Connect Disconnecting Detail
2	TCP/UDP_Client1/NTRIP Server1	192.168.3.18:9900		Unconnected	Connect Disconnecting Detail
3	TCP/UDP_Client2/NTRIP Server2	192.168.3.18:9901		Unconnected	Connect Disconnecting Detail
4	TCP/UDP_Client3/NTRIP Server3	192.168.3.18:9902		Unconnected	Connect Disconnecting Detail
5	TCP/UDP_Client4/NTRIP Server4	192.168.3.18:9903		Unconnected	Connect Disconnecting Detail
6	TCP/UDP_Client5/NTRIP Server5	192.168.3.18:9904		Unconnected	Connect Disconnecting Detail
7	TCP/UDP_Client6/NTRIP Server6	192.168.3.18:9905		Unconnected	Connect Disconnecting Detail
8	TCP Server/NTRIP Caster1	9901		Closed	Connect Disconnecting Detail
9	TCP Server/NTRIP Caster2	9902		Closed	Connect Disconnecting Detail
10	TCP Server/NTRIP Caster3	9903		Closed	Connect Disconnecting Detail
11	TCP Server/NTRIP Caster4	9904		Closed	Connect Disconnecting Detail
12	Serial Port	115200			Settings
13	Bluetooth	GNSS-3225804	GPGGA:5s,		Settings

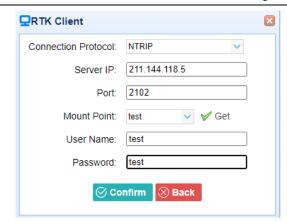
In this submenu, users can configure 6 types of input and output settings.

#### 1. RTK Client

After configuring the settings of RTK client, users can log on CORS or APIS. Tap the **Connect** button to the right  $\rightarrow$  the *IO Settings* screen will appear  $\rightarrow$  choose one of the connection protocols among the NTRIP, APIS\_BASE, APIS\_ROVER and TCP  $\rightarrow$  configure the related parameters  $\rightarrow$  click  $\bigcirc$  **Confirm** to log on CORS or APIS.

Connection Protocol: NTRIP





Connection Protocol: APIS\_BASE

RTK Client		×
Connection Protocol:	APIS_BASE 🗸	
Server IP:	111.111.111.1	
Port:	9901	
Differential Data:	OFF 🗸	
⊗ Co	onfirm 🛞 Back	

Connection Protocol: APIS\_ROVER

<b>Q</b> RTK Client		×
Connection Protocol:	APIS_ROVER V	
Server IP:	210.14.66.58	
Port:	9902	
Base ID:	1019923 🗸	
⊗ co	nfirm 🛞 Back	

Connection Protocol: TCP



RTK Client		Ð
Connection Protocol:	TCP 🗸	
Server IP:	201.255.122.215	
Port:	9902	
⊗ Co	nfirm 🛞 Back	

#### 2. TCP/UDP\_Client/NTRIP Server

Tap the **Connect** button on the right of required TCP/UDP Client  $\rightarrow$  the *IO Settings* screen will appear  $\rightarrow$  select the connection protocol from TCP, UDP,NTRIP1.0 and NTRIP2.0  $\rightarrow$  enter the IP and Port of the target server  $\rightarrow$  configure messages that you want to output to the target server  $\rightarrow$  click  $\bigcirc$  **Confirm** to save and complete the connection.

Connection Protocol: TCP

P/UDP Client					
Auto connect:			Connection Protocol:	TCP	~
Server IP:	192.168.3.18				
Port:	9900				
Differential Data:	OFF	~			
Raw Data:	OFF 🗸		HCPPP Data:	OFF	~
HRC Data:	OFF	~			
GPGGA:	OFF	~	GPGSV:	OFF	~
GPRMC:	OFF	~	GPZDA:	OFF	~
GPGST:	OFF	~	GPVTG:	OFF	~
GPGSA:	OFF	~			
Retransmit:	RTK V OFF	F 🗸			
		🔗 Confirm	⊗ Back		

Connection Protocol: UDP



TCP/UDP Client					X
Auto connect:			Connection Protocol:	UDP 🗸	
Server IP:	192.168.3.18		]		
Port:	9900		]		
Differential Data:	OFF	~			
Raw Data:	OFF 🗸		HCPPP Data:	OFF 🗸	
HRC Data:	OFF	~			
GPGGA:	OFF	~	GPGSV:	OFF 🗸	
GPRMC:	OFF	~	GPZDA:	OFF 🗸	
GPGST:	OFF	~	GPVTG:	OFF 🗸	
GPGSA:	OFF	~			
Retransmit:	RTK 🗸	OFF 🗸			
		6	Confirm 🛞 Back		
		C	Back		

Connection Protocol: NTRIP1.0

TCP/UDP Client				×
Auto connect:		Connection Protocol:	NTRIP1.0 V	
Server IP:	192.168.3.18			
Password:	••••••	Port:	9900	
Mount Point:		Differential Data:	OFF 🗸	
Raw Data:	OFF 🗸	HCPPP Data:	OFF 🗸	
HRC Data:	OFF 🗸			
GPGGA:	OFF 🗸	GPGSV:	OFF 🗸	
GPRMC:	OFF 🗸	GPZDA:	OFF 🗸	
GPGST:	OFF 🗸	GPVTG:	OFF 🗸	
GPGSA:	OFF 🗸			
Retransmit:	RTK V OFF V			
		Confirm 🛞 Back		
		Juck		

Connection Protocol: NTRIP2.0



TCP/UDP Client				×
Auto connect:		Connection Protocol:	NTRIP2.0	
Server IP:	192.168.3.18	User Name:	link_a	
Password:	••••••	Port:	9900	
Mount Point:		Differential Data:	OFF 🗸	
Raw Data:	OFF 🗸	HCPPP Data:	OFF 🗸 🗸	
HRC Data:	OFF	~		
GPGGA:	OFF	GPGSV:	OFF 🗸	
GPRMC:	OFF	GPZDA:	OFF 🗸	
GPGST:	OFF	GPVTG:	OFF 🗸	
GPGSA:	OFF	<b>~</b>		
Retransmit:	RTK V OFF	<b>~</b>		
		⊗ Confirm ⊗ Back		



#### 3. TCP Server/NTRIP Caster

Tap the **Connect** button to the right of required TCP Server/NTRIP Caster  $\rightarrow$  the **IO Settings** screen will appear  $\rightarrow$  select one of the connection protocols between NTRIP and TCP  $\rightarrow$  configure the other related parameters  $\rightarrow$  click  $\bigcirc$  **Confirm** to save the settings and open the server.

Connection Protocol: TCP

	_			
Auto connect:		Connection Protocol:	TCP	~
Port:	9901			
Differential Data:	OFF	<ul> <li>Raw Data:</li> </ul>	OFF 🗸	
HCPPP Data:	OFF	✓ HRC Data:	OFF	~
GPGGA:	OFF	V GPGSV:	OFF	~
GPRMC:	OFF	V GPZDA:	OFF	~
GPGST:	OFF	V GPVTG:	OFF	~
GPGSA:	OFF	~		
Retransmit:	274			
Retransmit	RTK 🗸 OFF	~		

Connection Protocol: NTRIP



TCP Server/NTRIP	Caster				l
Auto connect:			Connection Protocol:	NTRIP	~
User Name:			Password:		
Port:	9901		Mount Point:		
Differential Data:	OFF	~	Raw Data:	OFF 🗸	
HCPPP Data:	OFF	~	HRC Data:	OFF	~
GPGGA:	OFF	~	GPGSV:	OFF	~
GPRMC:	OFF	~	GPZDA:	OFF	~
GPGST:	OFF	~	GPVTG:	OFF	~
GPGSA:	OFF	~			
Retransmit:	RTK V OF	F 🗸			
		⊘ Confirm	n 🛞 Back		
		0.00			

#### 4. Bluetooth

Tap the **Settings** button to the right of Bluetooth  $\rightarrow$  the *Bluetooth Set* screen will appear  $\rightarrow$  configure the messages that you want to transmit through Bluetooth  $\rightarrow$  click  $\bigcirc$  confirm to save the settings and start to transmit.

Bluetooth Settin	gs		
Differential Data:	OFF 🗸	Raw Data:	OFF V
HCPPP Data:	OFF 🗸	HRC Data:	OFF 🗸
GPGGA:	5s 🗸	GPGSV:	OFF 🗸
GPRMC:	OFF 🗸	GPZDA:	OFF 🗸
GPGST:	OFF 🗸	GPVTG:	OFF 🗸
GPGSA:	OFF 🗸		
		Confirm Back	



# 4.6 Module Setting Menu

Use this menu to check module information, configure WiFi, bluetooth, radio related settings.



## 4.6.1 Description Submenu

Use this submenu to check the information of WiFi module, bluetooth module and radio module.

WI-FI Information		Radio Information	
Power Status:	ON	Radio Type:	Integ
Wifi Mode:	Access Point	Radio Power:	1W
MAC:	b4:bc:7c:2e:89:46	OTA Baud Rate:	9600
Access Point Details		Radio Frequency:	463.8125MHz
SSID:	GNSS-3269707	Radio Protocol:	Transparent
		Radio Frequency Channel:	Full Range
		Frequency Range	410MHz470MHz

### 4.6.2 WiFi Submenu

Use this submenu to turn on/off WiFi function and modify password.



WiFi ×	
WiFi	
Power Status:	
Auto Start:	Yes No
Internet:	
Wifi Mode:	Access Point
SSID:	GNSS-3225804
Encryption Type:	WAP
Password:	
🛄 s	tart

## 4.6.3 Bluetooth Settings Submenu

Bluetooth Settings ×			
Bluetooth Settings	]		
	GNSS-3225804 50:72:24:60:C7:6F		
	1234		
Save			

Use this submenu to turn on/off bluetooth function and modify PIN number.

## 4.6.4 Radio Settings Submenu

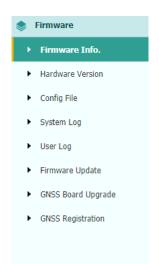
Use this submenu to turn on/off radio function and configure radio parameters.



Radio Settings ×	
Radio Settings	
Radio Status: OF	
Auto Start:	) Yes  No
Radio Protocol:	Transparent V
Channel Bandwidth :	25 ~ (kHz)
OTA Baud Rate:	9600 ~
Radio Power:	1W ~
Radio Frequency:	9 463.8125 (410MHz 470MHz)
	Save

## 4.7 Firmware Menu

Use this menu to check the current firmware information, download the system log, update the receiver firmware, download or update the configuration file and register the receiver, and more:





## 4.7.1 Firmware Info Submenu

Use this submenu to check the current firmware information. The following figure shows an example of the firmware information.

1 II III Wal C 1110. ^	
Firmware Version:	2.1.2
Firmware Release Time:	20201127_15084_5439

## 4.7.2 Hardware Version Submenu

Use this submenu to check the hardware information, including main board version and core board version:

Hardware Version ×	
Main Board:	1.1
Core Board:	1.1
PN:	A10654430005050004
Board Firmware Version Number:	R3.00Build20868

## 4.7.3 Config File Submenu

Use this submenu to update Configuration File.

Config File ×	
Download Configuration File :	と Download
Update Configuration File:	Browse
	🛄 Confirm



## 4.7.4 System Log Download Submenu

Use this submenu to download the system log of the receiver.

System Log ×	
System Log Type:	Firmware Log
ٹ	Download

### 4.7.5 User Log Submenu

Use this submenu to download the user log. Tap **Download** to download current user log; Tick items that you want to see on the user log and tap confirm button to confirm selected user log.

r Log ×	oad User Log: 쓰 Download			
User	Log settings			
1	System Starting Time	-	Wi-Fi Status	
1	External Power Removed	-	Bluetooth status	
1	Satellites Tracking Status Changed	-	CORS and APIS states	
1	TCP Client Connection	-	3g Connection status	
1	TCP Client Disconnect			
1	Observation Recording Start and End			
1	FTP file pushed			
1	Email alert time			
	⊗ Confirm			

### 4.7.6 Firmware Update Submenu

Use this submenu to load new firmware to the receiver across the network. Tap the **Browse** button to locate the upgrade file  $\rightarrow$  tap **Confirm** button to confirm the selected upgrading file and start upgrading.



Firmware Update ×		
	Upgrade File:	Browse
		Confirm

#### Notes

- It may take about 3 or 4 minutes to complete the firmware upgrading. Do not touch the power button or unplug the power until the upgrading process finishes, or damage will be caused to the receiver.
- The receiver will restart after the firmware upgrading is done, so users need to reconnect the receiver with your computer via Wi-Fi, and then log-in the receiver through a web browser to continue the configuration.

#### 4.7.7 GNSS Board Upgrade Submenu

Use this submenu to upgrade GNSS Board. Use this submenu to load new board to the receiver across the network. Tap the **Browse** button to locate the upgrade file  $\rightarrow$  tap **Confirm** button to confirm the selected upgrading file and start upgrading.

GNSS Board Upgrade ×	
Upgrade File:	Browse
	🖳 Confirm

### 4.7.8 GNSS Registration Submenu

Use this submenu to register the receiver. Paste or enter the registration code to the *Registration Code* field  $\rightarrow$  tap **Registration** button to complete the registration.



GNSS Registration ×		
Serial Number:	3269707	
Registration Limit:	2020-10-31	
Registration Code:	cHvbNNdWUMR	



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Stronger signal, easy to fix